



# ACOPOS 6D

Multidimensional motion for adaptive manufacturing



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## Challenges in product manufacturing

Product proliferation  
and smaller batch size

Shorter product lifecycles

Unpredictable  
demand fluctuation

Mass customization

## Today's challenges





## Adaptive manufacturing pillars



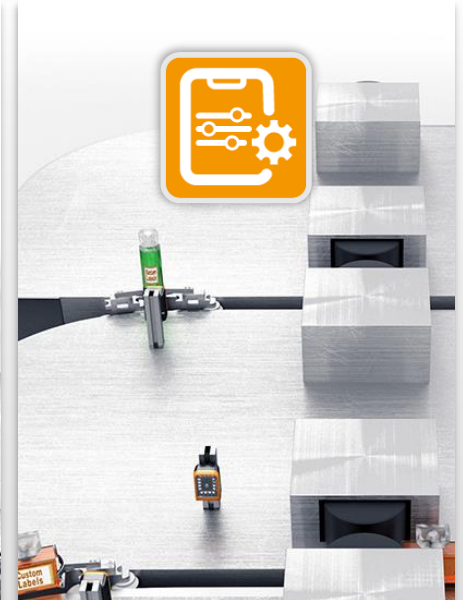
Zero-downtime  
changeover



Ready for unknown  
future products



High productivity  
and accelerated  
time-to-market



Profitable  
small-batch  
production

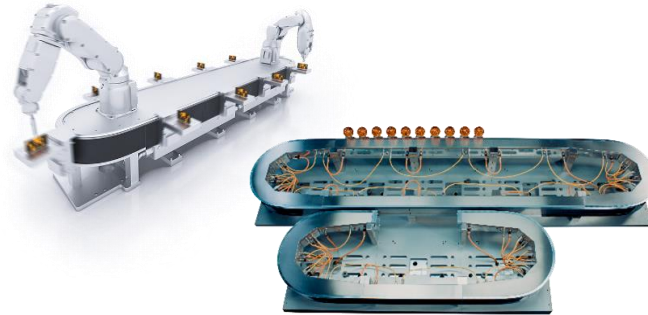


## Complete portfolio for adaptive manufacturing



# 1D

single / double / triple axes  
multi axes  
cabinet or field mounting  
induction / servo / dc / stepper motors  
from 100W up 500kW



# 2D

free definition of trak layout  
fully electromagnetic diverter  
independent movement of shuttles  
extremely high position accuracy  
hygienic design  
up to 10kg load



# 3-6D

arm / scara / delta robot  
robot controller part of the machine PLC  
1  $\mu$ s jitter  
fast reaction  
easy synchronization  
small footprint



## Reaktionsfähigkeit in Echtzeit

### Vision

Das integrierte Vision-System ermöglicht eine frühzeitige Auswertung von Produkt und Qualität

Durch die Integration wird das Ergebnis mit dem Track-System in Echtzeit ausgetauscht und erlaubt eine Prozessanpassung im laufenden Betrieb

Individuelle Produktkontrolle ermöglicht Track & Trace und die Rückverfolgbarkeit in Echtzeit









## Strategic cooperation with Planar Motor Inc (PMI)

### Partner

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Planar Motor Inc. (PMI),

- Headquartered in Vancouver Canada
- Founded in 2017
- Spin-off from the University of British Columbia

Main founder Dr. Xiaodong Lu researches since more than 15 years at the university of British Columbia and MIT in the field of magnetically-levitated planar motion technology

Key success factors

- Very innovative and dynamic company
- Strong IP portfolio
- Most superior product developed in the market so far

### Cooperation

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Basis

- Strategic cooperation agreement
- B&R is second largest/significant shareholder in planar Motor Inc. and holds specific shareholder right including board seat.

Areas of cooperation

- R&D
- Manufacturing
- Marketing, Sales and Support



## Smart movements

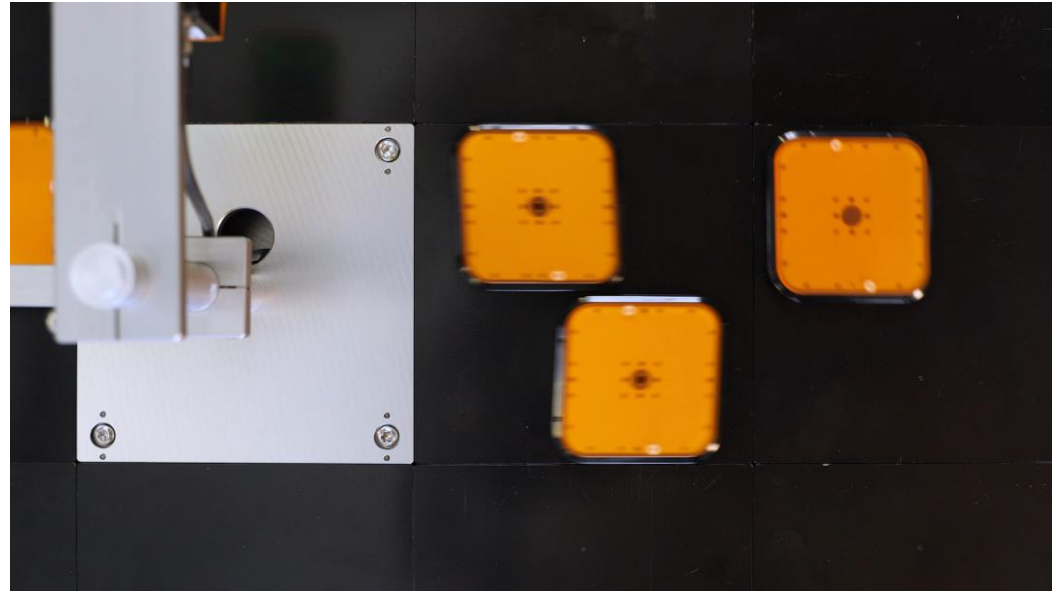
### 6 degree of freedom movements

X, Y

### Flexible movement commands

Linear, Arc, Short Axis, Pre-built Trajectory

Cyclic set position



## Smart movements

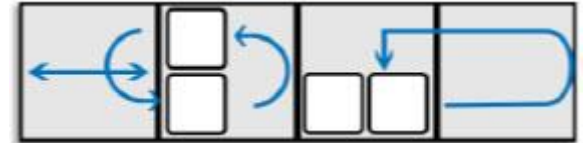
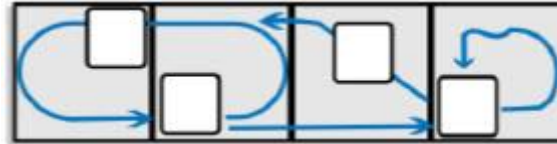
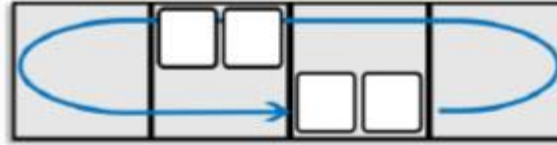
### 6 degree of freedom movements

X, Y

### Flexible movement commands

Linear, Arc, Short Axis, Pre-built Trajectory

Cyclic set position



## Smart movements

### 6 degree of freedom movements

X, Y

Z

### Z axis movement

Levitation up to 4mm

Force control



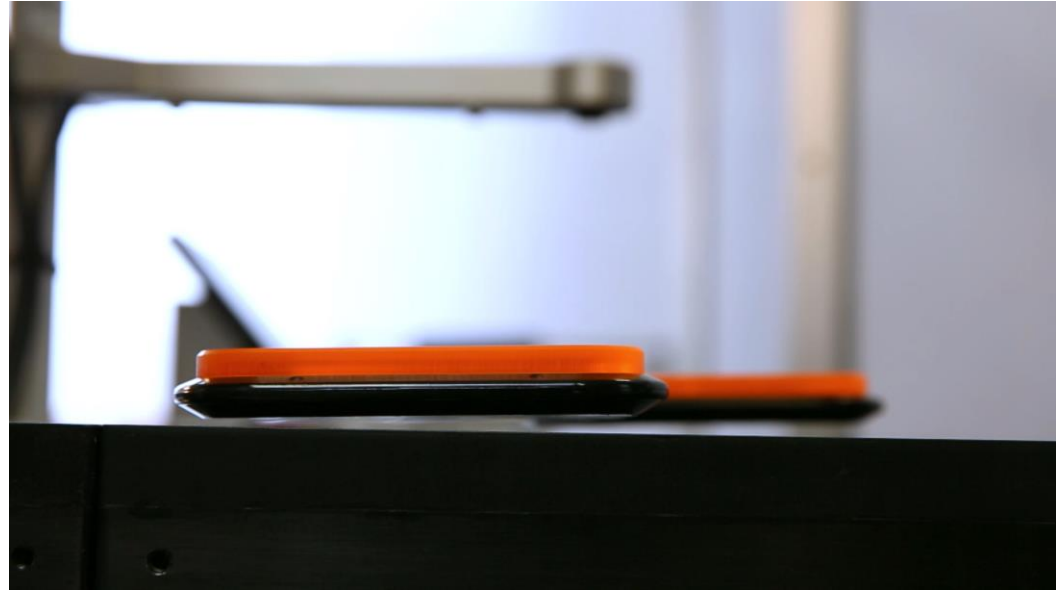
## Smart movements

### 6 degree of freedom movements

X, Y

Z

RX (pitch), RY (roll)





## Smart movements

### 6 degree of freedom movements

X, Y

Z

RX (pitch), RY (roll)

RZ (yaw)



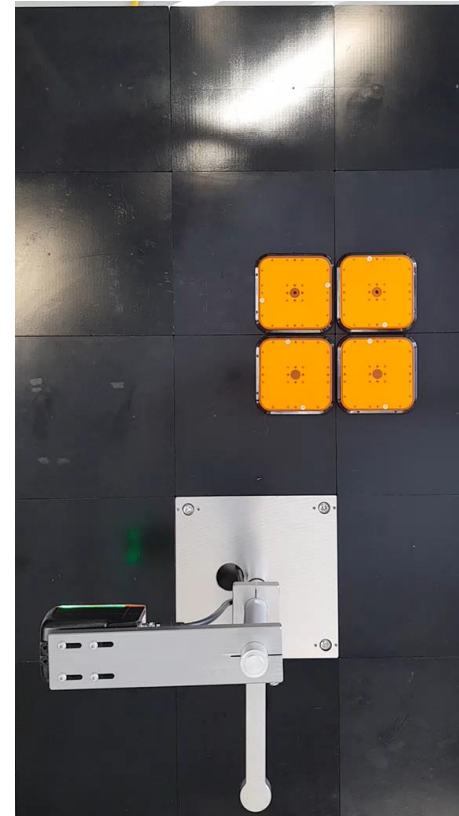


## Convoy

### Virtual linking

One virtual shuttles for controlling multiple shuttles

Convoy of shuttles





# ACOPOS 6D

## Shuttles interaction

### Relative movement between shuttle

Additional flexibility



## Shuttles interaction

### Optimized working space

Multiple parallel processes





## System components

### Segment

Coils and electronic

Complete design freedom for planar motor layout

Dimensions: 240 x 240 x 70 mm

Natural cooling / water cooling

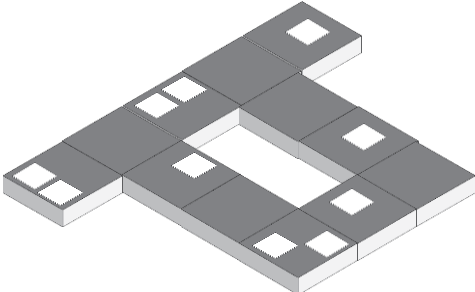
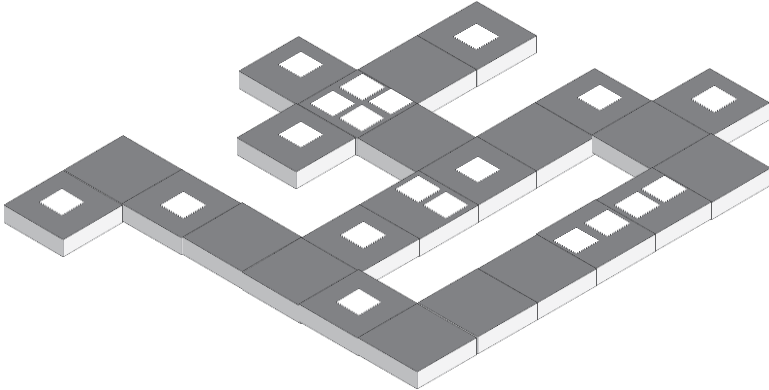
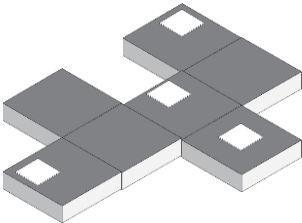
Daisy chain connection to other segments for power and fieldbus

48Vdc – 60Vdc power supply





## Unlimited layout possibility





## System components

### Shuttle

Equipped with permanent magnets (no electronic on board)

Movement on segment surface

Controlled independently

### Contactless motion

No mechanical guides

Maintenance free

No friction, no wear

### Position sensors included

Absolut position for each shuttle

No homing needed

Unique identifiable shuttle, no additional hardware needed





## System components

### Shuttle

Scalable system

Different payload, force and torque

Dimension [mm]	Payload [kg]*	Fx-y-z [N]	Tx-y-z [Nm]
120 x 120 x 10	0.6	12	0.3
120 x 180 x 10	1.0	20	0.5
120 x 240 x 10	1.5	30	1.0
180 x 180 x 10	1.8	36	1.25
180 x 210 x 10	2.0	40	1.5
210 x 210 x 10	2.4	48	2
240 x 240 x 10	3.6	72	3.5
210 x 330 x 12	4.2	84	4.5
300 x 300 x 12	6.0	120	8
330 x 330 x 12	7.2	144	10
450 x 450 x 16	14.4	288	30

\* 1mm levitation, payload center of gravity aligned with the center of the shuttle



Speed	2m/s
Acceleration	20m/s <sup>2</sup>
Repeatability	+/- 5µm
Flying height	0,5 – 4 mm
Rotation X, Y	< 20mrad
Rotation Z	< 20°



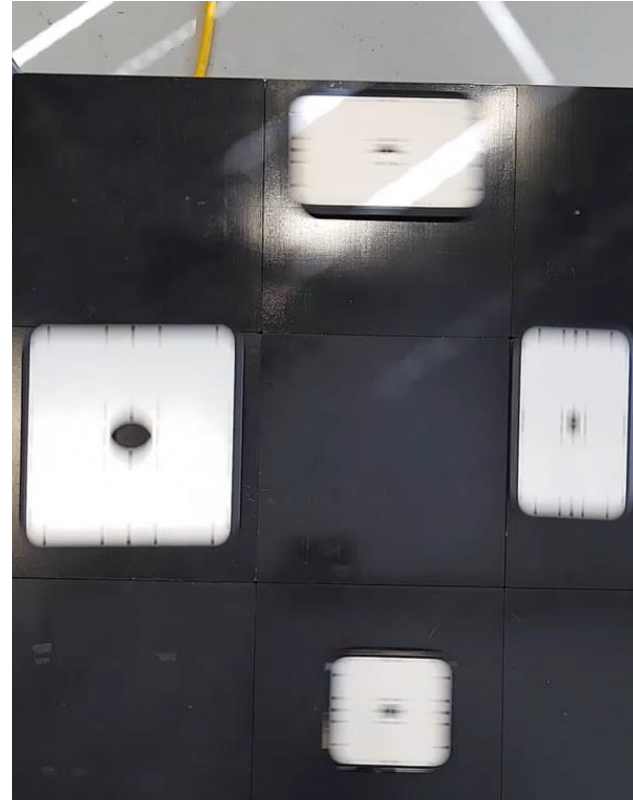


## System components

### Shuttle

Scalable system

Unlimited possibility to mix shuttles type





## System components

### ACOPOS 6D Controller

Shuttle path generation

Collision avoidance

Boundary checks

Integrated segments & shuttles simulation

Powerlink controlled node

Up to 200 segments & 50 shuttles (@ 800 $\mu$ s)

Synchronization between multiple ACOPOS  
6D Controllers

Dimensions: 152 x 207 x 36 mm



# ACOPOS 6D



Works everywhere

## Hygienic design

Stainless steel cover of standard segments

Stainless steel shuttle, without holes



## Robust

Maintenance free

Fanless

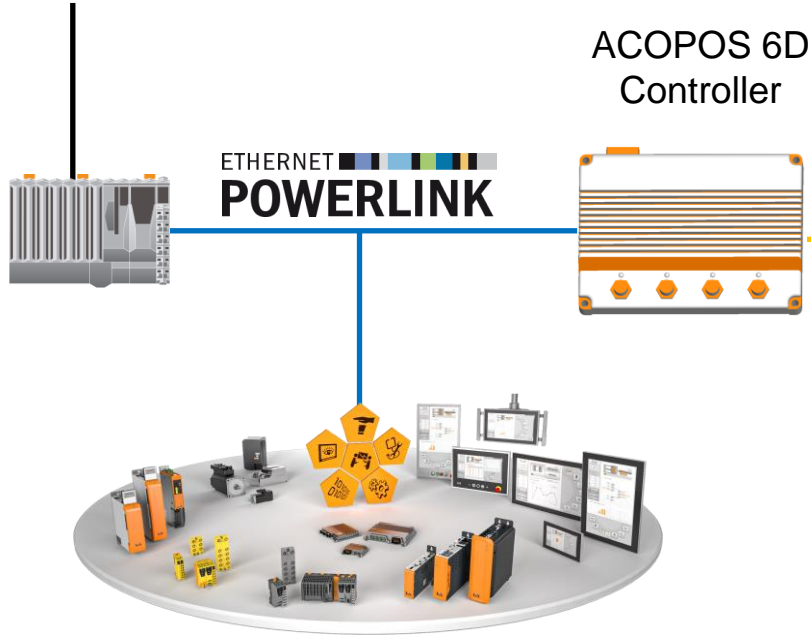
Contactless motion



# ACOPOS 6D

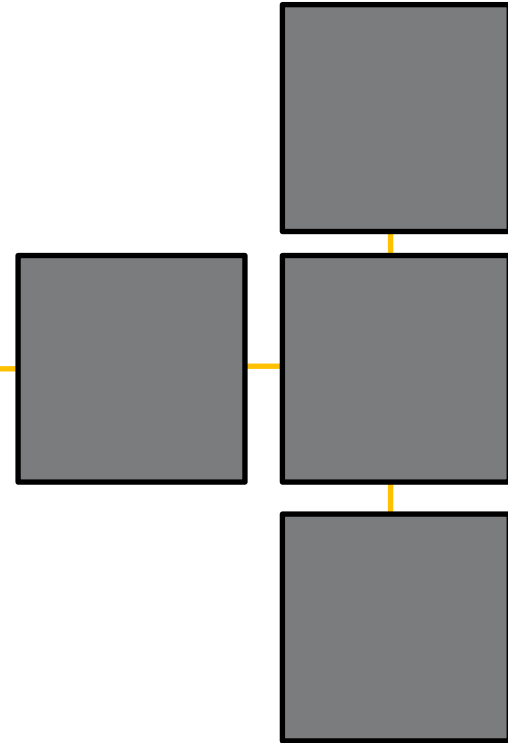


## Network topology



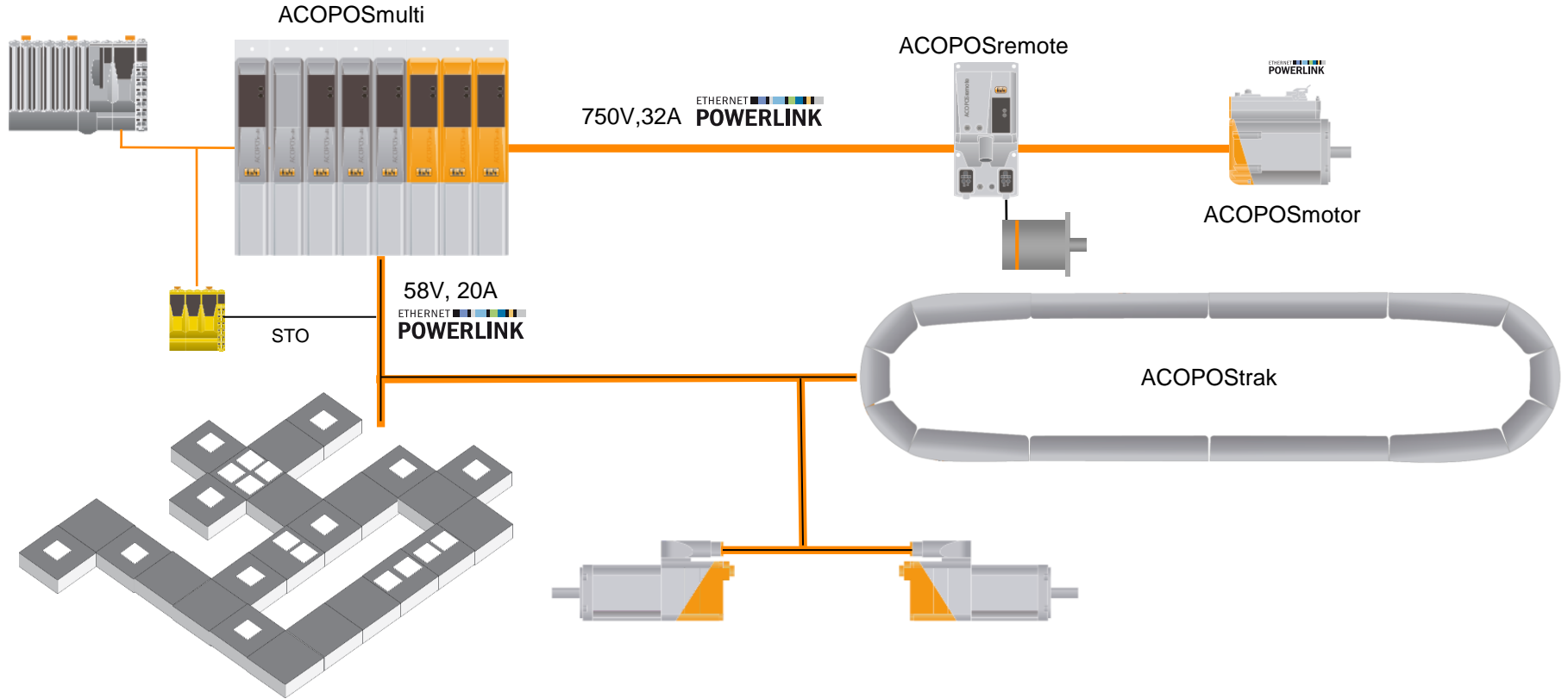
ACOPOS 6D  
Link

## Segments



# ACOPOS 6D

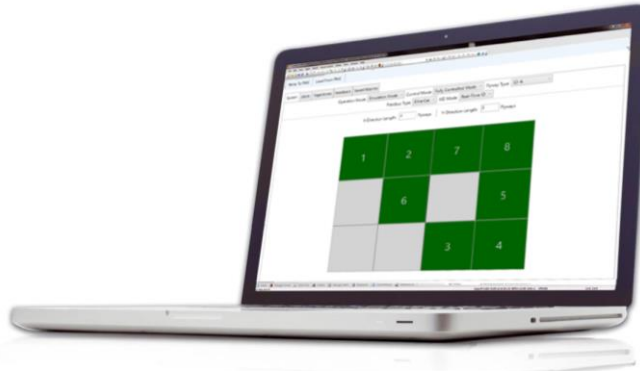
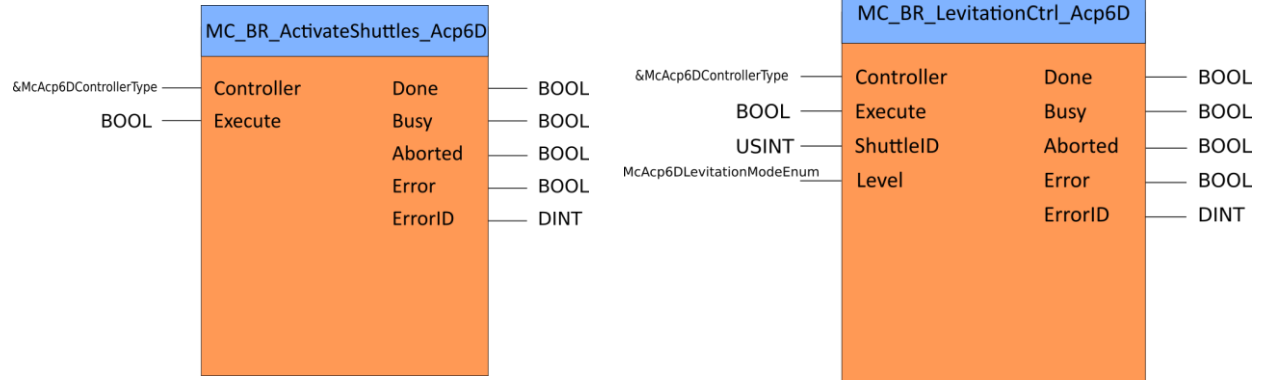
## Power supply topology



## Software

### ACOPOS 6D controller

- Powerlink slave
- Hardware configuration
- Automation Studio library
- PLCopen / mapp6D





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